

Deterministic and Exact Fully-dynamic Minimum Cut of Superpolylogarithmic Size in Subpolynomial Time



Antoine El-Hayek
ISTA



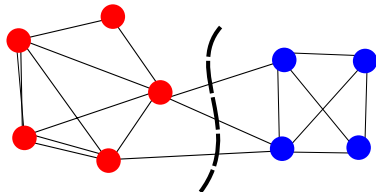
Monika Henzinger
ISTA



Jason Li
CMU

The Minimum Cut Problem

- ▶ Given a Graph $G = (V, E)$, partition V into V_1 and V_2 minimizing the number of crossing edges.
- ▶ Parallel edges are allowed
- ▶ Dynamic updates: Insertion and deletion of edges
- ▶ We denote by λ the value of the minimum cut.



Minimum Cut results

In the **static** case:

Reference	Running Time	Deterministic	Weighted
Karger (2000)	Near-linear time	No	Yes
Kawarabayashi, Thorup (2015)	Near-linear time	Yes	No
Henzinger, Rao, Wang (2020)	Near-linear time	Yes	No
Henzinger, Li, Rao, Wang (2024)	Near-linear time	Yes	Yes

Dynamic Minimum Cut Results

For **Dynamic Exact** minimum cut:

Reference	Upd. Time	Deterministic	Conditions
Henzinger (1997)	$O(\lambda \log n)$	Yes	Incremental
Thorup (2007)	$\tilde{O}(\lambda^{14.5} \sqrt{n})$	Yes	None
Goranci, Henzinger, Thorup (2018)	$\tilde{O}(1)$	Yes	Incremental
Goranci, Henzinger, Nanongkai, Saranurak, Thorup, Wulff-Nilsen (2023)	$\tilde{O}(m^{30/31})$	Yes	None
Jin, Sun, Thorup (2024)	$n^{o(1)}$	Yes	$\lambda \leq (\log n)^{o(1)}$
de Vos, Christiansen (2025)	$\tilde{O}(\lambda^{5.5} \sqrt{n}), \tilde{O}(m^{11/12})$	Yes	None
El-Hayek, Henzinger, Li (2026)	$n^{o(1)}$	Yes	$\lambda \leq 2^{\Theta(\log^{3/4-c} n)}$

Dynamic Minimum Cut Results

For **Dynamic Approximate** minimum cut:

Reference	Upd. Time	Approx. Ratio	Weighted	Det.
Thorup, Karger (2000)	$\tilde{O}(\lambda^2)$	$\sqrt{2 + o(1)}$	No	Yes
Thorup (2007)	$\tilde{O}(\sqrt{n})$	$1 + \frac{1}{\log^{0.05} n}$	No	Yes
Goranci, Räcke, Saranurak, Tan (2021)	$n^{o(1)}$	$n^{o(1)}$	No	Yes
van den Brand, Chen, Kyng, Liu, Meierhans, Gutenberg, Sachdeva (2024)	$n^{o(1)}$	$n^{o(1)}$	Yes	Yes
El-Hayek, Henzinger, Li (2025)	$n^{o(1)}$	$1 + \frac{1}{\log^{0.25} n}$	No	No
El-Hayek, Henzinger, Li (2026)	$n^{o(1)}$	$1 + 2^{-\Theta(\log^{3/4-c} n)}$	Yes	No

Derandomising LocalKCut

LocalKCut is a data structure:

- ▶ **Preprocessing:**

- ▶ Input: An unweighted graph G , a volume ν , a maximum cut value $\lambda_{\max}$
- ▶ Running time: $m^{1+o(1)}$

- ▶ **Query:**

- ▶ Input: a vertex $v \in G$
- ▶ Output: a set $\mathcal{S}$ of **all** cuts S that satisfy:
 - ▶ $v \in S$
 - ▶ $\text{Vol}(S) \leq \nu$
 - ▶ $\text{Cut}(S) \leq \lambda_{\max}$
- ▶ Query time: $n^{o(1)}$

Where $\text{Vol}(S) = \sum_{v \in S} \deg(v)$

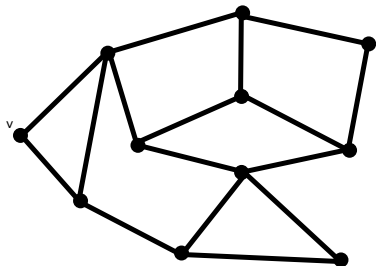


Figure: An example with $\nu = 9$ and $\lambda_{\max} = 3$

Derandomising LocalKCut

LocalKCut is a data structure:

- ▶ **Preprocessing:**

- ▶ Input: An unweighted graph G , a volume ν , a maximum cut value $\lambda_{\max}$
- ▶ Running time: $m^{1+o(1)}$

- ▶ **Query:**

- ▶ Input: a vertex $v \in G$
- ▶ Output: a set $\mathcal{S}$ of **all** cuts S that satisfy:
 - ▶ $v \in S$
 - ▶ $\text{Vol}(S) \leq \nu$
 - ▶ $\text{Cut}(S) \leq \lambda_{\max}$
- ▶ Query time: $n^{o(1)}$

Where $\text{Vol}(S) = \sum_{v \in S} \deg(v)$

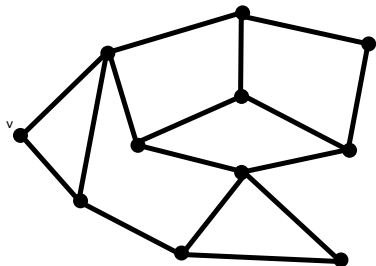


Figure: An example with $\nu = 9$ and $\lambda_{\max} = 3$

Derandomising LocalKCut

LocalKCut is a data structure:

- ▶ **Preprocessing:**

- ▶ Input: An unweighted graph G , a volume ν , a maximum cut value $\lambda_{\max}$
- ▶ Running time: $m^{1+o(1)}$

- ▶ **Query:**

- ▶ Input: a vertex $v \in G$
- ▶ Output: a set $\mathcal{S}$ of **all** cuts S that satisfy:
 - ▶ $v \in S$
 - ▶ $\text{Vol}(S) \leq \nu$
 - ▶ $\text{Cut}(S) \leq \lambda_{\max}$
- ▶ Query time: $n^{o(1)}$

Where $\text{Vol}(S) = \sum_{v \in S} \deg(v)$

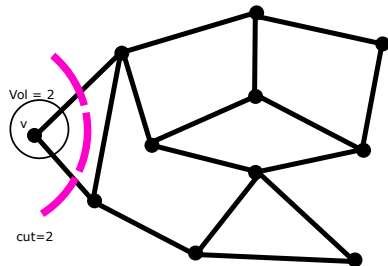


Figure: An example with $\nu = 9$ and $\lambda_{\max} = 3$

Derandomising LocalKCut

LocalKCut is a data structure:

- ▶ **Preprocessing:**

- ▶ Input: An unweighted graph G , a volume ν , a maximum cut value $\lambda_{\max}$
- ▶ Running time: $m^{1+o(1)}$

- ▶ **Query:**

- ▶ Input: a vertex $v \in G$
- ▶ Output: a set $\mathcal{S}$ of **all** cuts S that satisfy:
 - ▶ $v \in S$
 - ▶ $\text{Vol}(S) \leq \nu$
 - ▶ $\text{Cut}(S) \leq \lambda_{\max}$
- ▶ Query time: $n^{o(1)}$

Where $\text{Vol}(S) = \sum_{v \in S} \deg(v)$

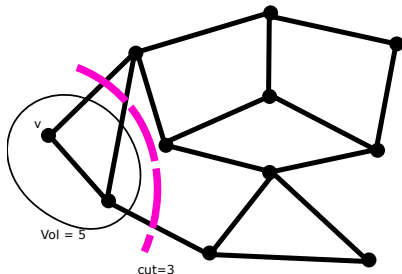


Figure: An example with $\nu = 9$ and $\lambda_{\max} = 3$

Derandomising LocalKCut

LocalKCut is a data structure:

- ▶ **Preprocessing:**

- ▶ Input: An unweighted graph G , a volume ν , a maximum cut value $\lambda_{\max}$
- ▶ Running time: $m^{1+o(1)}$

- ▶ **Query:**

- ▶ Input: a vertex $v \in G$
- ▶ Output: a set $\mathcal{S}$ of **all** cuts S that satisfy:
 - ▶ $v \in S$
 - ▶ $\text{Vol}(S) \leq \nu$
 - ▶ $\text{Cut}(S) \leq \lambda_{\max}$
- ▶ Query time: $n^{o(1)}$

Where $\text{Vol}(S) = \sum_{v \in S} \deg(v)$

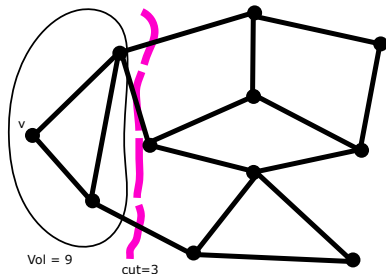
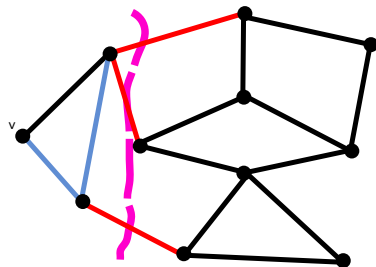


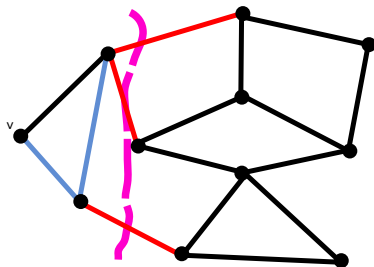
Figure: An example with $\nu = 9$ and $\lambda_{\max} = 3$

Derandomising LocalKCut: Main Idea



- ▶ Assume we have a coloring of the edges into blue and red edges such that:
 - ▶ There exists a tree in S whose edges are all blue
 - ▶ The edges crossing S are all red
- then a simple BFS starting at v easily finds S in time $O(\nu)$.

Derandomising LocalKCut: Main Idea



- ▶ Assume we have a coloring of the edges into blue and red edges such that:
 - ▶ There exists a tree in S whose edges are all blue
 - ▶ The edges crossing S are all redthen a simple BFS starting at v easily finds S in time $O(\nu)$.
- ▶ Assume we have $n^{o(1)}$ many colorings with at least one of them satisfying the above property, running a BFS for each coloring also finds S

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

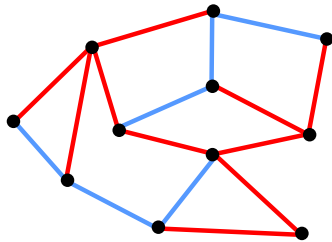


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

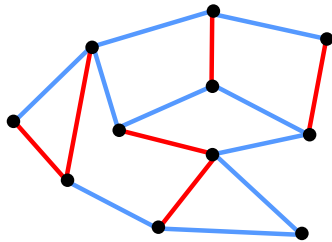


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

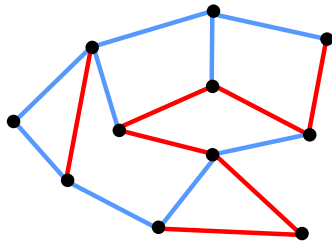


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

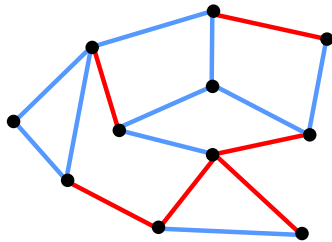


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

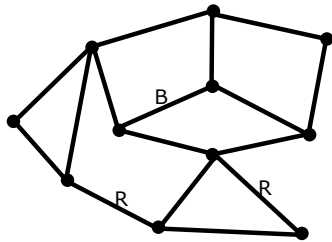


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

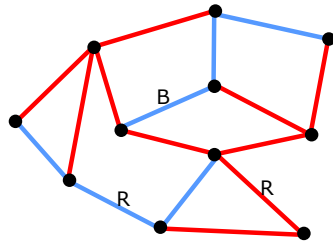


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

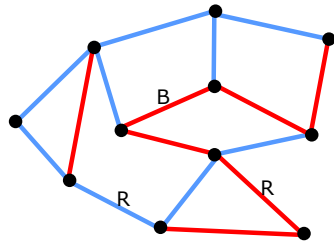


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

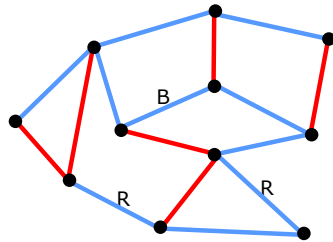


Figure: example for $r = 2$ and $b = 1$

Creating Colorings

Theorem [Chitnis, Cygan, Hajiaghayi, Pilipczuk, Pilipczuk 2016]

Let $G = (V, E)$ be a graph and $r, b \in \mathbb{N}$. There exists a family of $N = (r + b)^{O(\min\{r, b\})} \log m$ red-blue colorings of the edges such that:

for any $R, B \subseteq E$, $R \cap B = \emptyset$, $|R| \leq r$, $|B| \leq b$, there exists a coloring where all edges in R are red and all edges in B are blue.

This family is computable in $N \cdot m$ deterministic time.

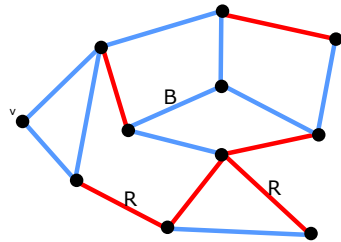
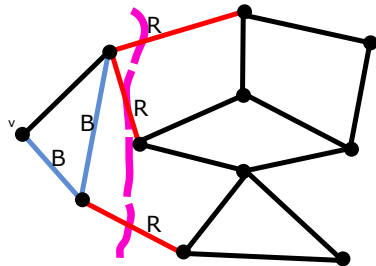


Figure: example for $r = 2$ and $b = 1$

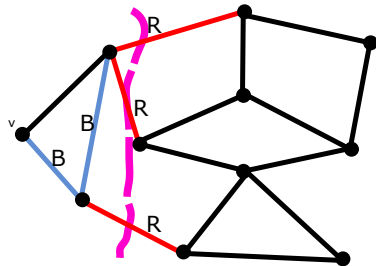
Creating Colorings

- ▶ **Attempt 1:** $r = \lambda_{\max}$, $b = \nu$, deterministic
LocalKCut would be trivial:
 - ▶ Simply make all edges of a tree in S blue and all edges crossing S red



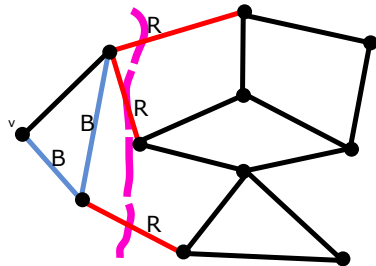
Creating Colorings

- ▶ **Attempt 1:** $r = \lambda_{\max}$, $b = \nu$, deterministic LocalKCut would be trivial:
 - ▶ Simply make all edges of a tree in S blue and all edges crossing S red
 - ▶ But then
$$N = (\lambda_{\max} + \nu)^{O(\min\{\lambda_{\max}, \nu\})} \cdot \log m \gg n^{o(1)}$$



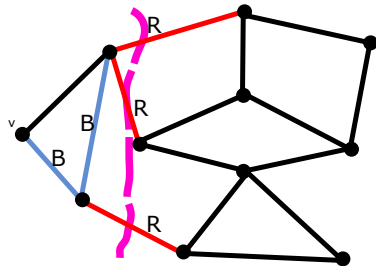
Creating Colorings

- ▶ **Attempt 1:** $r = \lambda_{\max}$, $b = \nu$, deterministic LocalKCut would be trivial:
 - ▶ Simply make all edges of a tree in S blue and all edges crossing S red
 - ▶ But then
$$N = (\lambda_{\max} + \nu)^{O(\min\{\lambda_{\max}, \nu\})} \cdot \log m \gg n^{o(1)}$$
- ▶ **Attempt 2:** we create a red-blue coloring with $r = 2\beta$, $b = \nu$, and a yellow-green coloring with $r = y = \lambda_{\max}$, $b = g = 2\beta$



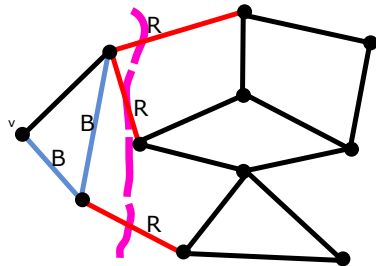
Creating Colorings

- ▶ **Attempt 1:** $r = \lambda_{\max}$, $b = \nu$, deterministic LocalKCut would be trivial:
 - ▶ Simply make all edges of a tree in S blue and all edges crossing S red
 - ▶ But then
$$N = (\lambda_{\max} + \nu)^{O(\min\{\lambda_{\max}, \nu\})} \cdot \log m \gg n^{o(1)}$$
- ▶ **Attempt 2:** we create a red-blue coloring with $r = 2\beta$, $b = \nu$, and a yellow-green coloring with $r = y = \lambda_{\max}$, $b = g = 2\beta$
 - ▶ $\beta = O(1)$ is a constant to determine later.
 - ▶ $N = \nu^{O(1)} = n^{o(1)}$, $N = \lambda_{\max}^{O(1)} = n^{o(1)}$ respectively

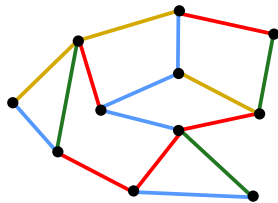
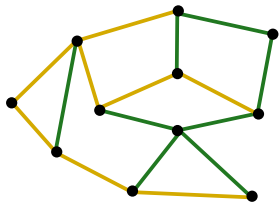
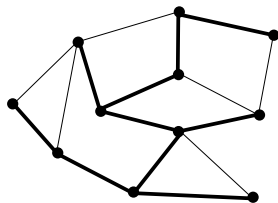
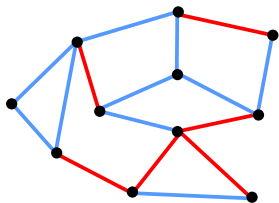


Creating Colorings

- ▶ **Attempt 1:** $r = \lambda_{\max}$, $b = \nu$, deterministic LocalKCut would be trivial:
 - ▶ Simply make all edges of a tree in S blue and all edges crossing S red
 - ▶ But then
$$N = (\lambda_{\max} + \nu)^{O(\min\{\lambda_{\max}, \nu\})} \cdot \log m \gg n^{o(1)}$$
- ▶ **Attempt 2:** we create a red-blue coloring with $r = 2\beta$, $b = \nu$, and a yellow-green coloring with $r = y = \lambda_{\max}$, $b = g = 2\beta$
 - ▶ $\beta = O(1)$ is a constant to determine later.
 - ▶ $N = \nu^{O(1)} = n^{o(1)}$, $N = \lambda_{\max}^{O(1)} = n^{o(1)}$ respectively
- ▶ We need to stitch the colorings together, using **Greedy Tree Packings**

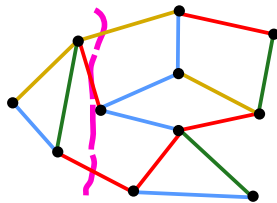
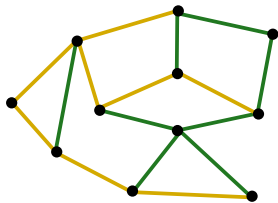
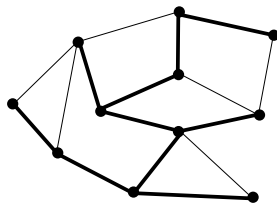
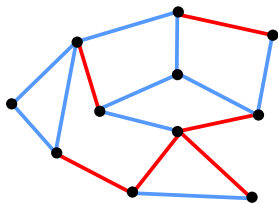


Trees and Coloring



Edges in the tree are colored in Red and Blue, others in Yellow and Green

Trees and Coloring

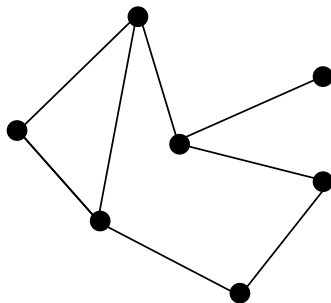


The BFS will run on two colors: Blue and Green, ignoring Red and Yellow

Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

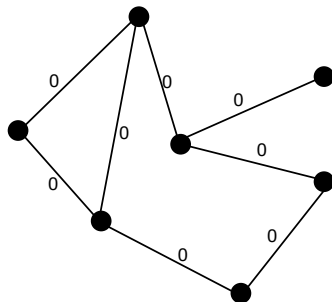
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

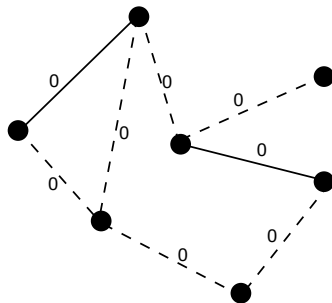
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

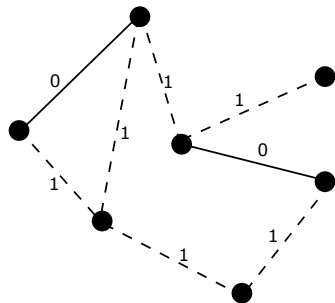
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

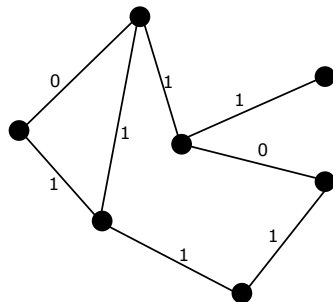
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

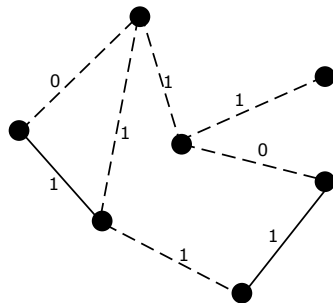
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

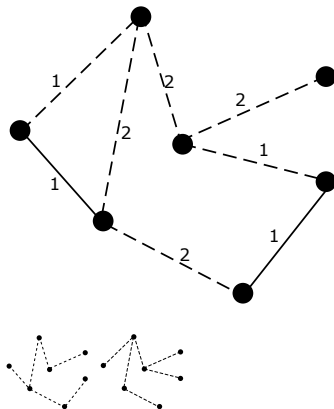
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

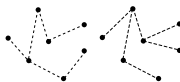
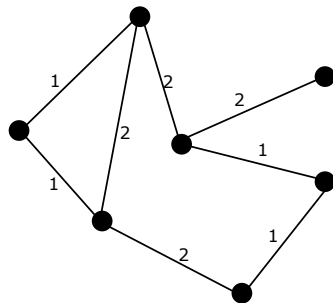
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

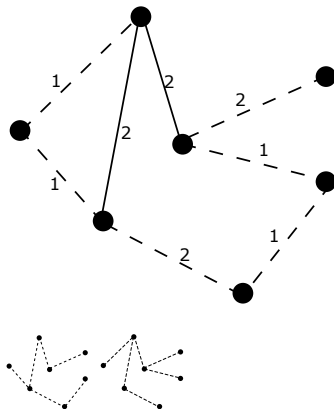
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

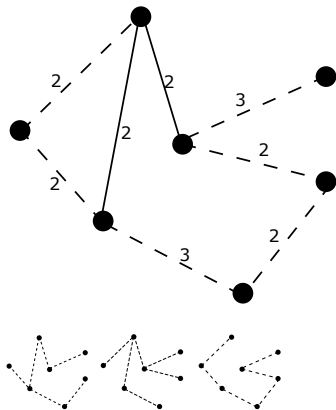
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

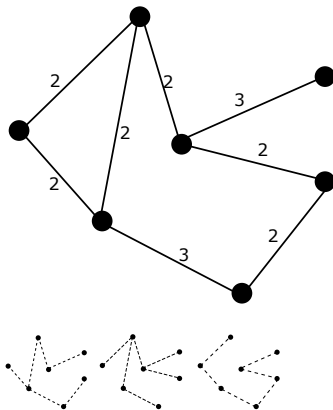
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

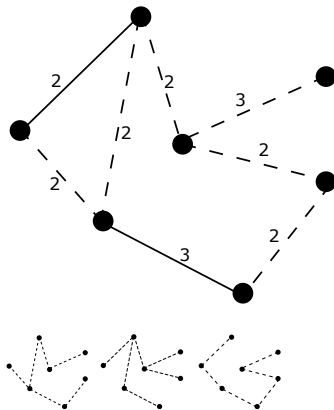
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

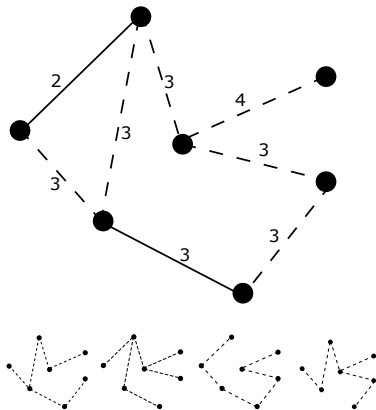
- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Greedy Tree Packing

A greedy tree packing of a graph G with k trees is a set of k trees obtained as follows:

- ▶ Set the weights of all the edges of G to 0
- ▶ Repeat k times:
 - ▶ Find a minimum spanning tree T of G
 - ▶ Add T to the packing
 - ▶ Increase the weight of every edge of T by one in G
- ▶ Return the packing



Trees k -respecting a cut

Definition

In a graph G , a tree is said to k -respect a cut if there are at most k edges crossing the cut.

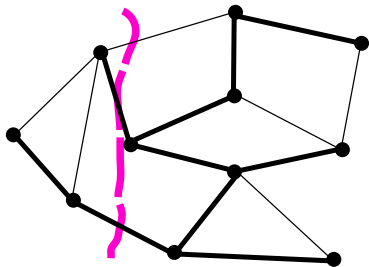


Figure: This tree 2-respects the cut

Trees k -respecting a cut

Definition

In a graph G , a tree is said to k -respect a cut if there are at most k edges crossing the cut.

Theorem [Karger 2000]

Let S be a minimum cut. If we choose $\Theta(\lambda \log m)$ trees in the greedy tree packing, there exists a tree that 2-respects S .

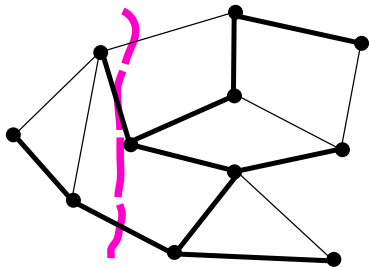


Figure: This tree 2-respects the cut

Trees k -respecting a cut

Definition

In a graph G , a tree is said to k -respect a cut if there are at most k edges crossing the cut.

Theorem [Karger 2000]

Let S be a minimum cut. If we choose $\Theta(\lambda \log m)$ trees in the greedy tree packing, there exists a tree that 2-respects S .

Theorem

Let S be a β -approximate minimum cut. If we choose $\Theta(\lambda \beta^2 \log m) = n^{o(1)}$ trees in the greedy tree packing, there exists a tree that 2β -respects S .

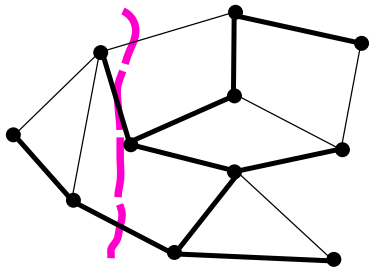
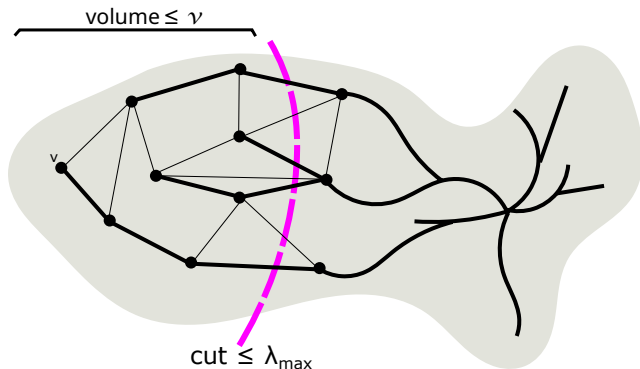


Figure: This tree 2-respects the cut

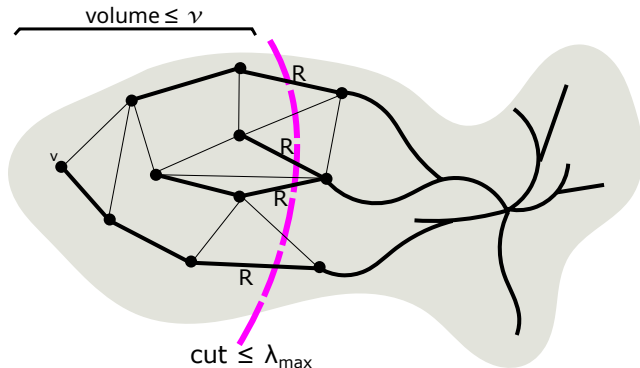
Putting things together

We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



Putting things together

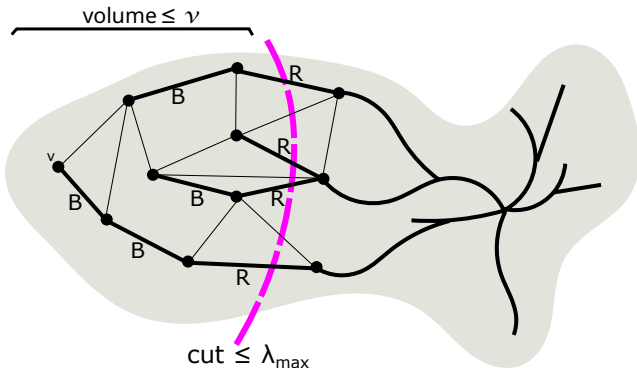
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



The tree is 2β -respecting the cut
 $\Rightarrow$ We can label all tree edges crossing the cut with "R"

Putting things together

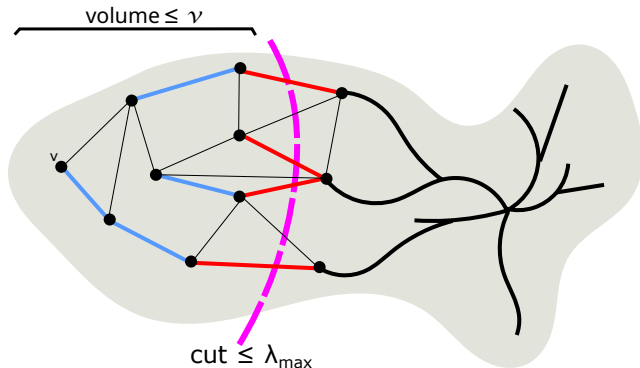
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



The volume of the tree inside S is at most ν
 $\Rightarrow$ We can label all tree edges inside S with "B"

Putting things together

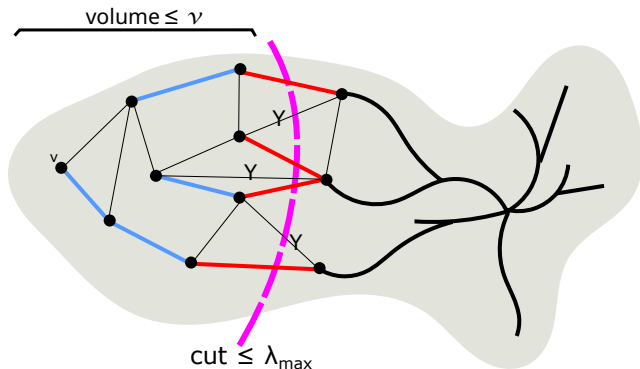
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



We can find a red-blue coloring that fits the labels

Putting things together

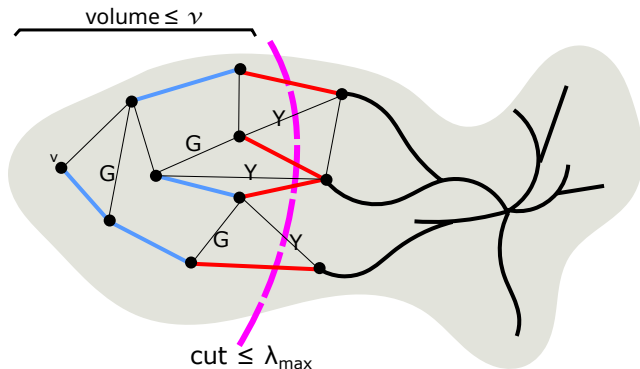
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



The total number of edges crossing the cut is at most $\lambda_{\max}$
 $\Rightarrow$ We can label all non-tree edges crossing S with "Y"

Putting things together

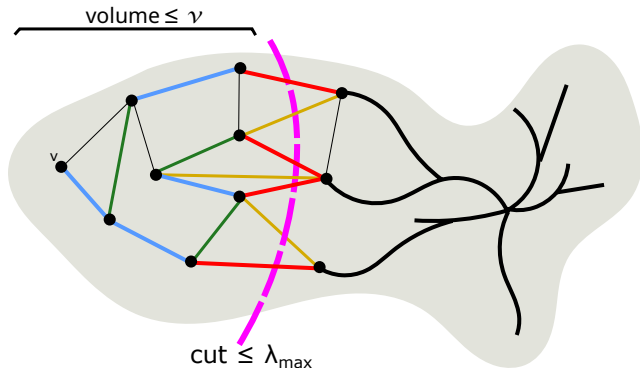
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



The blue edges inside S form at most 2β components
 $\Rightarrow$ We can connect them with at most 2β many edges outside the tree, labeling them "G"

Putting things together

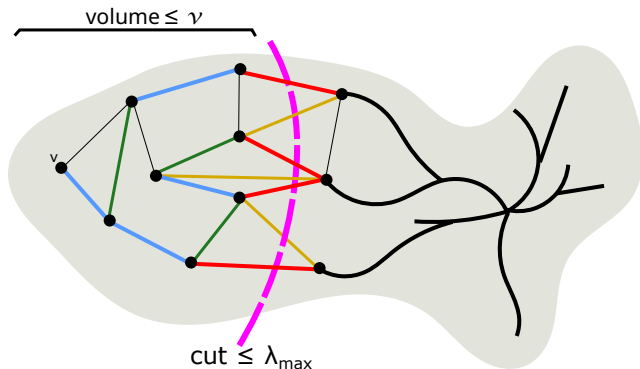
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



We can find a yellow-green coloring that fits the labels

Putting things together

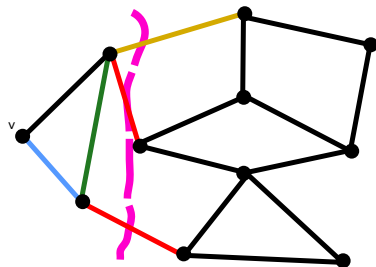
We can choose $r = 2\beta$ red edges, $b = \nu$ blue edges, $y = \lambda_{\max}$ yellow edges, and $g = 2\beta$ green edges.



The Deterministic LocalKCut Data Structure

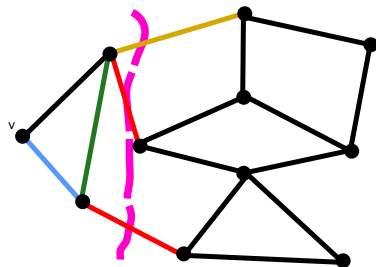
- ▶ Preprocessing:
 - ▶ Compute Red-Blue and Yellow-Green Colorings
 - ▶ Compute a Greedy Tree Packing
- ▶ Upon Request:
 - ▶ For every (R-B coloring, Y-G coloring, Tree):
 - ▶ Color all edges in the tree according to the R-B coloring
 - ▶ Color all edges outside the tree according to the Y-G coloring
 - ▶ Do a BFS on Blue and Green edges, starting on v , limiting the volume explored to ν
 - ▶ If the BFS ends on a set that satisfies the required conditions, add it to the set of cuts to return
- ▶ Return the set found

Request time Analysis



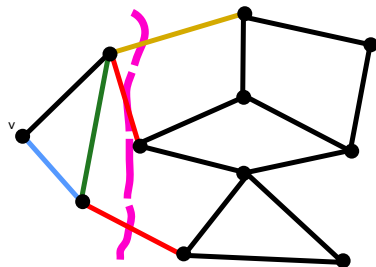
- ▶ We have:
 - ▶ $n^{o(1)}$ many red-blue colorings
 - ▶ $n^{o(1)}$ many yellow-green colorings
 - ▶ $n^{o(1)}$ many trees

Request time Analysis



- ▶ We have:
 - ▶ $n^{o(1)}$ many red-blue colorings
 - ▶ $n^{o(1)}$ many yellow-green colorings
 - ▶ $n^{o(1)}$ many trees
- ▶ For each tuple of two colorings and a tree, we construct a red-blue-yellow-green coloring

Request time Analysis



- ▶ We have:
 - ▶ $n^{o(1)}$ many red-blue colorings
 - ▶ $n^{o(1)}$ many yellow-green colorings
 - ▶ $n^{o(1)}$ many trees
- ▶ For each tuple of two colorings and a tree, we construct a red-blue-yellow-green coloring
- ▶ Overall, we need to run $(n^{o(1)})^3$ BFS each of which runs in $n^{o(1)}$ time.

Conclusion

Theorem 1

For **unweighted** graphs, we give a **deterministic** fully-dynamic algorithm that can maintain the **exact** minimum cut in $n^{o(1)}$ update time as long as $\lambda \leq 2^{\Theta(\log^{3/4-c} n)}$.

Theorem 2

For **positively, real-weighted** graphs, we give a **randomised** fully-dynamic algorithm that can maintain a $\left(1 + 2^{-\Theta(\log^{3/4-c} n)}\right)$ -**approximate** minimum cut in $n^{o(1)}$ update time.

Open questions:

1. Can we extend the exact algorithm to all values of λ ?
2. What about the directed case?
3. What about the exact weighted case? the deterministic weighted case?